

REFERENCES

- [1] (2012, June) ASIMO by Honda. [Online]. <http://asimo.honda.com/>
- [2] David Kurniawan, *DESIGN AND DEVELOPMENT OF KINEMATICS SYSTEM MODEL FOR BIPEDAL ROBOT.*, 2011.
- [3] Kåre Halvorsen. (2012, June) Zenta Robotic Creations. [Online]. <http://robot-kits.org/category/archer/>
- [4] Tzoo-Hseng S. Li, Yu-Te Su, Shao-Wei Lai, and Jhen-Jia Hu, "Walking Motion Generation, Synthesis, and Control for Biped Robot by Using PGRL, LPI, and Fuzzy Logic," June 2011.
- [5] Qiang Huang et al., "Planning Walking Patterns for a Biped Robot," June 2001.
- [6] Michael Negnevitsky, *Artificial Intelligence: A guide to Intelligence Systems*, Second Edition ed. London: ADDISON WESLEY, 2005.
- [7] Gerald Wahyudi Setiono, *KINEMATIC MODEL ANALYSIS AND DEVELOPMENT OF WALKING ALGORITHM FOR 5 DEGREE OF FREEDOM BIPEDAL ROBOT.*, 2012.
- [8] (2012, June) [Online]. <http://www.joliebrisemodels.co.uk/tenth/servo.html>
- [9] (2012, June) Mathworks. [Online]. <http://www.mathworks.com/help/toolbox/fuzzy/fp49243.html>