

REFERENCES

- [1] R. Van Hook, N. Baine, Dr. K. Rattan, and Dr. J. Gallagher. Moogie the Robotic Lawnmower. Available at: http://robomow.ion.org/wp-content/uploads/2011/12/2011_WSU2_Moogie.pdf
- [2] John-David Warren, Josh Adams, Harald Molle. Arduino Robotics. Apress, 2011
- [3] Viktor P. Astakhov & Xinran Xiao (2008). A Methodology for Practical Cutting Force Evaluation Based on The Energy Spent in the Cutting System. ISSN: 1091-0344 print/1532-2483 online. Machining Science and Technology. Available from: <http://www.astvik.com/publications/AstXiao2008.PDF>
- [4] Todd Layt & Ian Paanen (2007). Quantifying the Strengthening of Soil by Commonly Used Landscape Plants and Turf. Available at: <http://www.ozbreed.com.au/download/research-papers/erosionpaper.pdf>
- [5] Mait, Wihelmin Meidy Rachel. (2007). Designing and Constructing an Automatic Robot Driver for Vacuum Cleaner. Bachelor Thesis. Swiss German University.
- [6] "History of Lawn Mower". http://www.american-lawns.com/history/history_mower.html, accessed April 21, 2013.
- [7] "Hall Effect Sensor". <http://www.electronics-tutorials.ws/electromagnetism/hall-effect.html>, accessed May 18, 2013.
- [8] "How do you calculate the average of a set of angle". <http://stackoverflow.com/questions/491738/how-do-you-calculate-the-average-of-a-set-of-angles>, accessed May 2013.