

REVERSE VENDING MACHINE AND CRUSHER INTEGRATION AND IMPROVEMENT

By

Vincent Zavellino
11701004



SWISS GERMAN UNIVERSITY

SWISS GERMAN UNIVERSITY

The Prominence Tower

Jalan Jalur Sutera Barat No. 15, Alam Sutera
Tangerang, Banten 15143 - Indonesia

Revision After Thesis Defense on 13/07/2021

STATEMENT BY THE AUTHOR

I hereby declare that this submission is of my own work and to the best of my knowledge, it contains no material previously published or written by another person, nor material which to a substantial extend has been accepted for any award of any other degree or diploma at any educational institution, except where due acknowledgement is made in the thesis.

Vincent Zavellino

Student

Approved by:

Erikson F Sinaga S.T. M.Kom

Date

Thesis Advisor

Date

SWISS GERMAN UNIVERSITY

Leonard P Rusli M.Sc. Ph.D

Thesis Co-Advisor

Date

Dr. Maulahikmah Galinium, M.Sc.

Dean

Date

Vincent Zavellino

ABSTRACT

REVERSE VENDING MACHINE AND CRUSHER INTEGRATION AND IMPROVEMENT

By

Vincent Zavellino
Erikson F Sinaga S. T. M.Kom, Advisor
Leonard P Rusli M.Sc. Ph.D, Co-Advisor

SWISS GERMAN UNIVERSITY



Waste management is a major issue in most Southeast Asian Countries, with nearly all forms of waste being unsorted. Plastic bottles and cans are one of the major reasons for pollution in Indonesia, these wastes usually go straight to a landfill instead of being recycled. With the Reverse Vending Machine, a user can redeem their deposit money previously paid during the purchase of the beverage, this promotes recycling of plastic bottles and cans, thus reducing the amount of waste in society.

The Crusher system paired with the RVM allows waste to be crushed and thus saves space which allows more waste to be stored in a waste bin before it needs emptying. The crushed waste also makes it easier to recycle into other forms. With this project, I hope to produce a better Reverse Vending Machine that can be implemented in Indonesia and help the waste management in Southeast Asia.

Keywords: Reverse Vending Machine, Crusher, Waste Management, Barcode Processing, Beverage, Pneumatic, Raspberry Pi

© Copyright 2021
by Vincent Zavellino
All rights reserved



DEDICATION

I dedicate this work for God, science and the environment.



ACKNOWLEDGEMENT

I would like to thank God for giving me the chance to study in SGU and making this thesis, my family for their support, and my friends for their support and assistance during the course of this thesis.

I also would like to thank my advisor Mr. Erikson F. Sinaga S.T. M.Kom for his guidance and patience, and my co-advisor Mr. Leonard P. Rusli, M.Sc, Ph.D. for his guidance and valuable ideas.



Special thanks to Mr. Y. Fredhi S.T, Mr. Dwi Karuna and Mr. Kristian Nova for their assistance during troubleshooting the RVM and Crusher, and my friends Nicolas Albert Witono, Dave Yolanda Oktavianus, Vinlen Aston Sidharta and Yongky Felix Christian for their support.

SWISS GERMAN UNIVERSITY

TABLE OF CONTENTS

| | |
|---|----|
| STATEMENT BY THE AUTHOR..... | 2 |
| ABSTRACT..... | 3 |
| DEDICATION..... | 5 |
| ACKNOWLEDGEMENT..... | 6 |
| TABLE OF CONTENTS..... | 7 |
| LIST OF FIGURES..... | 9 |
| LIST OF TABLES..... | 11 |
| CHAPTER 1 - INTRODUCTION..... | 12 |
| 1.1 Background and Problem Statement..... | 12 |
| 1.2 Significance of Study..... | 13 |
| 1.3 Thesis Objectives..... | 13 |
| 1.4 Thesis Scopes and Limitations..... | 13 |
| CHAPTER 2 - LITERATURE REVIEW..... | 14 |
| 2.1 Theoretical Perspectives..... | 14 |
| 2.1.1 Reverse Vending Machine..... | 14 |
| 2.1.2 Crusher..... | 15 |
| 2.2 Projects Related to Thesis Work..... | 15 |
| 2.2.1 Simulation of an RVM Using Xilinx 14.5 ISE Simulator..... | 15 |
| 2.2.2 The Accuracy of Garbage Detection..... | 16 |
| 2.2.3 SGU's Previous RVM and Crusher..... | 16 |
| CHAPTER 3 - DESIGN AND METHODOLOGY..... | 18 |
| 3.1 Conceptual Design..... | 18 |
| 3.2 Existing Condition..... | 20 |
| 3.2.1 RVM Gears..... | 22 |
| 3.2.2 RVM Roller..... | 23 |
| 3.2.3 Conveyor Motor and Gear Plate..... | 23 |
| 3.2.4 RVM Roller Plate..... | 24 |
| 3.2.5 Photoelectric Sensor BTF30-DDTL-P..... | 25 |
| 3.2.6 Inductive Proximity Sensor LJ12A3-4-Z/BY..... | 25 |
| 3.3 Proposed Mechanical Design..... | 26 |
| 3.3.1 Gear Design..... | 27 |
| 3.3.2 Polyurethane Round Belt..... | 28 |
| 3.3.3 Crusher Piercer..... | 29 |
| 3.4 Design Calculation and/or Modeling..... | 30 |
| 3.4.1 Plastic Bottle Crushing Force..... | 31 |
| 3.4.2 Can Crushing Force..... | 33 |
| 3.5 Program Design..... | 34 |
| CHAPTER 4 - TESTING AND DISCUSSION OF RESULTS..... | 45 |
| 4.1 Overview of Prototype Performance..... | 45 |
| 4.2 Testing and Experimental Plans..... | 45 |
| 4.3 Test Results..... | 46 |
| 4.3.1 Crusher Mechanical and Electrical Test Results..... | 46 |
| 4.3.2 RVM and Crusher Integration..... | 54 |
| 4.3.3 RVM Electrical Test Results..... | 55 |
| 4.3.4 Mobile App Algorithm Test Results..... | 57 |
| 4.4 Discussion of Test Results and Error Diagnoses..... | 66 |

| | |
|--|-----|
| 4.4.1 Crusher Test Result Discussion..... | 66 |
| 4.4.2 Mobile App QR Code Scan Result Discussion..... | 66 |
| 4.4.3 Full Testing Result Discussion..... | 67 |
| CHAPTER 5 - CONCLUSIONS AND RECOMMENDATIONS..... | 70 |
| 5.1 Conclusions..... | 70 |
| 5.2 Recommendations..... | 71 |
| GLOSSARY..... | 72 |
| REFERENCES..... | 73 |
| CURRICULUM VITAE..... | 74 |
| Appendix A - Mechanical Design..... | 75 |
| Appendix B - Datasheets..... | 87 |
| Appendix C - Program Codes..... | 127 |
| Appendix D - Bill of Materials..... | 140 |



LIST OF FIGURES

| | |
|--|----|
| Figure 2.1 TOMRA S1 Rugged Reverse Vending Machine..... | 14 |
| Figure 2.2 A 3D rendering of a typical Crusher | 15 |
| Figure 2.3 The previous generation RVM prototype | 17 |
| Figure 3.1 Research Framework..... | 18 |
| Figure 3.2 RVM Block Diagram..... | 19 |
| Figure 3.3 Crusher System Block Diagram..... | 20 |
| Figure 3.4 3D printed gear for the RVM..... | 22 |
| Figure 3.5 3D printed Roller for the RVM | 23 |
| Figure 3.6 3D printed Motor and Gear Plate..... | 24 |
| Figure 3.7 3D printed Roller Plate..... | 24 |
| Figure 3.8 Photoelectric sensor..... | 25 |
| Figure 3.9 Inductive proximity sensor..... | 26 |
| Figure 3.10 27 teeth gear 3D design..... | 27 |
| Figure 3.11 29 teeth gear 3D design..... | 28 |
| Figure 3.12 PU Round Belt..... | 29 |
| Figure 3.13 3D design of the new piercer..... | 30 |
| Figure 3.14 Free body diagram of a bottle during crushing..... | 30 |
| Figure 3.15 Research Flowchart diagram..... | 34 |
| Figure 3.16 UML chart for credits process..... | 35 |
| Figure 3.17 UML chart for history process..... | 36 |
| Figure 3.18 UML chart of the transaction process..... | 37 |
| Figure 3.19 Start screen code block part 1..... | 38 |
| Figure 3.20 Start screen code blocks part 2..... | 39 |
| Figure 3.21 Start screen code blocks part 3..... | 39 |
| Figure 3.22 Sign up screen code blocks..... | 40 |
| Figure 3.23 Home screen code blocks..... | 41 |
| Figure 3.24 Scan screen code blocks..... | 41 |
| Figure 3.25 History screen code blocks..... | 42 |
| Figure 3.26 Transaction screen code blocks..... | 42 |
| Figure 3.27 Redeem screen code blocks..... | 43 |
| Figure 3.28 Credits screen code blocks..... | 43 |
| Figure 3.29 Firebase database structure..... | 44 |
| Figure 3.30 Firebase database rules..... | 44 |
| Figure 4.1 Bottles were unable to be penetrated and crushed properly..... | 49 |
| Figure 4.2 Bottles were poked before being dropped into the waste chute..... | 50 |
| Figure 4.3 Old pneumatic cylinder head..... | 50 |
| Figure 4.4 Crushed bottles..... | 52 |
| Figure 4.5 Cans were successfully crushed..... | 53 |
| Figure 4.6 RVM and Crusher integration..... | 54 |
| Figure 4.7 RVM and Crusher integration side view..... | 55 |
| Figure 4.8 Start screen result..... | 58 |
| Figure 4.9 Sign up screen result..... | 59 |
| Figure 4.10 Home screen result..... | 59 |
| Figure 4.11 Scan screen result..... | 60 |
| Figure 4.12 History screen result..... | 61 |

| | |
|--|----|
| Figure 4.13 Redeem history screen result..... | 62 |
| Figure 4.14 Transaction history screen result..... | 62 |
| Figure 4.15 Credits screen result..... | 63 |
| Figure 4.16 QR code scanning example..... | 64 |
| Figure 4.17 QR code scan result example..... | 65 |



LIST OF TABLES

| | |
|--|----|
| Table 3.1 Plastic bottle masses..... | 31 |
| Table 3.2 Aluminium can masses..... | 33 |
| Table 4.1 500ml plastic bottle detection result..... | 47 |
| Table 4.2 1.5L plastic bottle detection result..... | 47 |
| Table 4.3 250ml can detection result..... | 48 |
| Table 4.4 330ml can detection result..... | 48 |
| Table 4.5 Plastic bottle crushing with new piercer result..... | 49 |
| Table 4.6 Bottle crushing result with the old cylinder head..... | 51 |
| Table 4.7 Can crushing result..... | 53 |
| Table 4.8 Laser non-interrupted test result..... | 56 |
| Table 4.9 Laser interrupted test result..... | 57 |
| Table 4.10 QR code scanning results..... | 65 |
| Table 4.11 RVM low barcode one cycle test result | 67 |
| Table 4.12 RVM high barcode one cycle test result..... | 68 |
| Table 4.13 Can crushing time result..... | 68 |
| Table 4.14 Bottle crushing time result..... | 68 |
| Table 4.15 QR code scan time result..... | 69 |

SWISS GERMAN UNIVERSITY