

**OPTIMIZING DELTA ARM ROBOT BY IMPLEMENTING ROBOT  
OPERATING SYSTEM – INDUSTRIAL (ROS-I) AND VISION-SYSTEM**

By

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11301003

BACHELOR'S DEGREE  
in

MECHANICAL ENGINEERING – MECHATRONICS CONCENTRATION  
FACULTY OF ENGINEERING AND INFORMATION TECHNOLOGY

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August 2017

Revision after the Thesis Defense on 25<sup>th</sup> July 2017

## STATEMENT BY THE AUTHOR

I hereby declare that this submission is my own work and to the best of my knowledge, it contains no material previously published or written by another person, nor material which to a substantial extent has been accepted for the award of any other degree or diploma at any educational institution, except where due acknowledgement is made in the thesis.

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## ABSTRACT

### OPTIMIZING DELTA ARM ROBOT BY IMPLEMENTING ROBOT OPERATING SYSTEM – INDUSTRIAL (ROS-I) AND VISION-SYSTEM

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The main purpose of this thesis is to implement Robot Operating System – Industrial (ROS-I) into the existing SGU's Delta Arm Robot. The ROS-I was used due to its emphasis of code reutilization and based on ROS which provides vast package library for robotics applications. The implementation consists of two main subsystems vision-system and robot movement which at the end create the whole structure of Delta Arm Robot to perform simple pick and place task. The vision-system was used to perform object detection and sent the appropriate coordinate information from the detected object into the robot movement system. In the robot movement system, then the information will be processed to manipulate the Delta Arm Robot. Existing hardware from the robot such as Dynamixel servo, conveyor belt, and the Delta Arm Robot parts were used in order to create those two subsystems. Additionally, new rotary end-effector and mechanical gripper were made for future development of the Delta Arm Robot. At the end, the result of this thesis was a system that can perform a simple pick and place task and indirectly improve the Delta Arm Robot from the existing one.

*Keywords: ROS-I, Delta Arm Robot, Vision System, End-Effector, Pick and Place, Dynamixel*



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## **DEDICATION**

In dedication to my parents, my advisor, Dr. Rusman Rusyadi, B.Eng., M.Sc, without whom this thesis would be incomplete and for the advancement of Indonesia`s automation industry.



## ACKNOWLEDGEMENTS

First of all, I am grateful to the God for the strength, good health, and well-being that were necessary to complete this thesis.

I wish to express my sincere thanks to Dr. Rusman Rusyadi B.Eng, M.Sc, my advisor, for sharing his expertise in robot programming, and valuable guidance and encouragement extended to me. I could not have imagined having a better advisor and mentor for my Bachelor study.

I am also grateful to Yohanes Freddy Pranoto, the SGU workshop superintendent. I am extremely thankful for providing me with all the necessary facilities for the thesis and guidance in utilizing Solidworks.

I place on record, my gratitude to Andreas Dhanu Saputra, Yohannes William, Matthew Judijanto, Daniel Setiono, and Andreas Meifyanno Dani, for their ideas and support in crucial moments while doing this thesis and good humor.

I take this opportunity also to express my sincere gratitude to all of the Mechatronics Department faculty members, lecturers and librarians, for their support and sharing knowledge throughout the Curriculum and Instruction program which is stimulating and thoughtful, enlighten me about the past and present ideas and issues.

Lastly, special thanks to F1Tenth Group, Workshop Group, and the rest of Mechatronics '13 students which have been filling my precious university life with joy, happiness and encouragement in every moment and fighting together throughout 8 overwhelming semesters.

Without all, who directly and indirectly have lent their hands, this thesis will not be completed.

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