

**IMPLEMENTATION OF LANE TRACKING SYSTEM WITH VISION ON
AUTONOMOUS RACING CAR USING ROBOT OPERATING SYSTEM**

By

Kevin Ariesta
11301025

BACHELOR'S DEGREE
in

MECHANICAL ENGINEERING - MECHATRONICS CONCENTRATION
FACULTY OF ENGINEERING AND INFORMATION TECHNOLOGY



SWISS GERMAN UNIVERSITY
The Prominence Tower, Alam Sutera
Jalan Jalur Sutera Barat No. 15
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Revision after Thesis Defense on 25th July 2017

STATEMENT BY THE AUTHOR

I hereby declare that this submission is my own work and to the best of my knowledge, it contains no material previously published or written by another person, nor material which to a substantial extent has been accepted for the award of any other degree or diploma at any educational institution, except where due acknowledgement is made in the thesis.

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ABSTRACT

IMPLEMENTATION OF LANE TRACKING SYSTEM WITH VISION ON AUTONOMOUS RACING CAR USING ROBOT OPERATING SYSTEM

By

Kevin Ariesta

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SWISS GERMAN UNIVERSITY

The objective of this thesis is to implement lane tracking system with vision on autonomous racing car using Robot Operating System. The main sensor of the lane tracking system is PS3 Eye Camera, which will be utilized as the vision system of the car. The lane tracking program will be supported with OpenCV library, which is the feature to process the captured image from the camera and enable lane detection system. In this lane tracking system, ROS will be utilized as the main software platform to execute all of the required packages for implementing the lane tracking system, such as the lane detection program and the controller. All of the software and program packages for this system will be stored in Nvidia Jetson Tegra K1 mini PC. Arduino will be used in this system as the controller for steering and drive motor. The testing of the lane tracking system will be limited only for detecting and following the white-coloured lane only.

Keywords: Lane Tracking System, Vision, Robot Operating System, PS3 Eye Camera, OpenCV, Nvidia Jetson Tegra K1 mini PC, Arduino.



DEDICATION

I dedicate this work for God Jesus Christ, myself, father, mother, Pak Rusman and Family, Aulia Syamil, Victor Nugraha Putera, and all of my friends and lecturers who contribute in helping me finish this final project.



ACKNOWLEDGEMENTS

I wish to thank you to God Jesus Christ for his blessing and guidance in finishing this thesis project.

I also wish to thank you to my father and my mother for their support in prayers, spirit, and finance.

Furthermore, I would like to present my gratitude for Dr. Rusman Rusyadi, B.Eng., M.Sc., as my thesis advisor for his guidance and his time in guiding me until this thesis project is done.

Finally, I also wish to thank you to all of my friends and lecturers for their help, especially my teammates, Aulia Syamil and Victor Nugraha Putera, who have been working on this thesis together with me.

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