## Measuring a Diameter for Transparent PET Plastic

By

Nicholas Juditra 11301030

#### **BACHELOR'S DEGREE**

in

MECHANICAL ENGINEERING – MECHATRONICS CONCENTRATION FACULTY OF ENGINEERING AND INFORMATION TECHNOLOGY

# SWISS GERNSCUIVERSITY

#### SWISS GERMAN UNIVERSITY

The Prominence Tower Jalan Jalur Sutera Barat No. 15, Alam Sutera Tangerang, Banten 15143 - Indonesia

August 2017

Revision after the Thesis Defense on July 26<sup>th</sup> 2017

# STATEMENT BY THE AUTHOR

I hereby declare that this submission is my own work and to the best of	of my knowledge,
it contains no material previously published or written by another pe	rson, nor material
which to a substantial extent has been accepted for the award of an	y other degree or
diploma at any educational institution, except where due acknowledge	gement is made in
the thesis.	
Nicholas Juditra	
Student	Date
Approved by:	
Dr. Rusman Rusyadi, B.Eng., M.Sc.  Thesis Advisor	Date
Leonard Priyatna Rusli, M.Sc., Ph.D.	
Thesis Co-Advisor	Date
Dr. Ir. Gembong Baskoro, M.Sc  Dean	Data
Dean	Date

#### **ABSTRACT**

#### MEASURING A DIAMETER FOR TRANSPARENT PET PLASTIC

By

Nicholas Juditra Dr. Rusman Rusyadi, B.Eng., M.Sc., Advisor Leonard Priyatna Rusli, M.Sc., Ph.D., Co-Advisor

#### **SWISS GERMAN UNIVERSITY**

The objective of this thesis is to develop a computer vision to detect a transparent plastic tray shape and measure a diameter of transparent plastic tray. Webcam camera is used to capture and record the transparent object image which is used as the main input image to be processed using Qt Creator and OpenCV library. Many image processing technique is used for this thesis such as, Background Subtraction, Blurring, Thresholding, Hough Transform, Canny, Find Contour, and Segmentation.

To achieve the objectives for detect and measure diameter of transparent plastic, two methods are used, find contour and segmentation. The result of find contour method has proved to be able to detect and measure the transparent tray object. The segmentation method also work, however the result is not satisfy because it cannot segment transparent plastic from it's background due to object transparency.

Keywords: Computer Vision, Transparent Plastic Tray, Qt Creator, OpenCV, Image Processing, findContour, and Segmentation.



## **DEDICATION**

I dedicate this works for my family, lecturers, and all of my friends.



#### **ACKNOWLEDGEMENTS**

.

I would like to thank my parents, who always encouraged me and support the financial needs for this thesis.

I would like to express my gratitude to Dr. Rusman Rusyadi, B.Eng., M.Sc. as advisor who was particularly helpful in guiding me throughout the entire thesis work. I also want to thank Mr. Leonard Priyatna Rusli, M.Sc., Ph.D., as my co-advisor, for assisting me during my thesis work.

Last but not least, I would like to thank all of my colleagues in Mechatronic batch 2013, who have been together for four years, experienced various periods of joy and sorrow together.

# **SWISS GERMAN UNIVERSITY**

# TABLE OF CONTENTS

	Page
STATEMENT BY THE AUTHOR	2
ABSTRACT	3
DEDICATION	5
ACKNOWLEDGEMENTS	6
TABLE OF CONTENTS	7
LIST OF FIGURES	
LIST OF TABLES	
CHAPTER 1 - INTRODUCTION	
1.1 Background	
1.2 Thesis Objectives	
1.3 Thesis Limitation and Scope	14
1.4 Problem Identification	
1.5 Significance of Study	
1.6 Thesis Structure	
CHAPTER 2 - LITERATURE REVIEW	
2.1 Computer Vision	16
2.2 Machine Vision	18
2.3 Difference between Computer Vision and Machine Vision	
2.4 Digital Image Processing	
2.4.1 Grayscale Conversion	
2.4.2 Background Subtraction	21
2.4.3 Image Smoothing	
2.4.4 Image Thresholding	
2.4.5 Morphological Transformations	
2.4.7 Contours	
2.4.8 Hough Transform	39
2.4.9 Image Segmentation with Watershed Algorithm	41
2.5 Related Work	42
CHAPTER 3 – RESEARCH METHODS	43

3.1 Materials and Equipment	
3.1.1 Qt/C++ Software Development Tool	
3.1.3 Camera	
3.1.4 Logitech Camera Setting	
3.1.5 LED Lamp	
3.1.6 Transparent Plastic Object	
3.2 Processing Methodology	49
3.2.1 findContour Method	
_	
3.3 Testing Plan  CHAPTER 4 – RESULTS AND DISCUSSIONS	
4.1 Lighting Test	
4.2 Initialization	
4.3. Computer Vision Testing and Result	
4.3.1 FindContour Method Result	
4.3.1.2 Capture Result with Transparent Object	
4.3.1.2 Background Subtraction Result	
4.3.1.3 Pre Processing Result	
4.3.1.4 Contour Method Result	
4.3.1.6 Hough Circle Result	
4.3.1.6 Circle Detection along with PutText Result	84
4.3.1.7 Circle Measurement Result	
4.3.2 Segmentation Method Result	
4.3.2.2 Distance Transform and Normalize	89
4.3.2.3 Threshold Binary and Dilate Function to Find "Pe	
	91
4.3.2.5 Watershed Result	
CHAPTER 5 – CONCLUSIONS AND RECCOMENDATIONS	
5.1 Conclusion	
5.2 Recommendation	98
GLOSSARY	99
REFERENCES	100
APPENDIX	102
APPENDIX A- PROGRAMMING CONTOUR CODE	103
APPENDIX B- PROGRAMMING WATERSHED CODE	109
APPENDIX C- BILL OF MATERIAL	114

CURRICULUM VITAE......115