

**IMPLEMENTATION OF DOUBLE-AXIS CLEANING MECHANISM AND
VISUAL INSPECTION TO IMPROVE THE PERFORMANCE OF SELF
CLEANING PHOTOVOLTAIC MODULE ROBOT**

By

Hagen Jevon Oszarwin
11301018

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SWISS GERMAN UNIVERSITY


SWISS GERMAN UNIVERSITY
The Prominence Tower
Jalan Jalur Sutera Barat No. 15, Alam Sutera
Tangerang, Banten 15143 - Indonesia

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STATEMENT BY AUTHOR

I hereby declare that this submission is my own work and to the best of my knowledge, it contains no material previously published or written by another person, nor material which to a substantial extent has been accepted for the award of any other degree or diploma at any educational institution, except where due acknowledgement is made in the thesis.

Hagen Jevon Oszarwin

Student

Date

Approved by:

Erikson Ferry S. Sinaga, ST, M.Kom

Thesis Advisor

Date

Dr. Irvan Kartawiria, S.T., M .Sc.

Dean

Date

Hagen Jevon Oszarwin

ABSTRACT

IMPLEMENTATION OF DOUBLE-AXIS CLEANING MECHANISM AND VISUAL INSPECTION TO IMPROVE THE PERFORMANCE OF SELF CLEANING PHOTOVOLTAIC MODULE ROBOT

By

Hagen Jevon Oszarwin
Erikson Ferry S. Sinaga, ST, M.Kom, Advisor

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The purpose of this thesis is to further develop the cleaning mechanism to improve the performance of energy harvesting for Photovoltaic module. In this thesis there are several implementations that are required to be done. The improvement of this project will be the implementation of double axis cleaning mechanism for the robot cleaner. The data taken will be stored in thinkspeak.

Keywords: PV panel, Self-Cleaning Robot, Energy Harvesting, Dual-Axis Mechanism

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DEDICATION

I dedicated this thesis project for the future of technology and development in all parts of the world.



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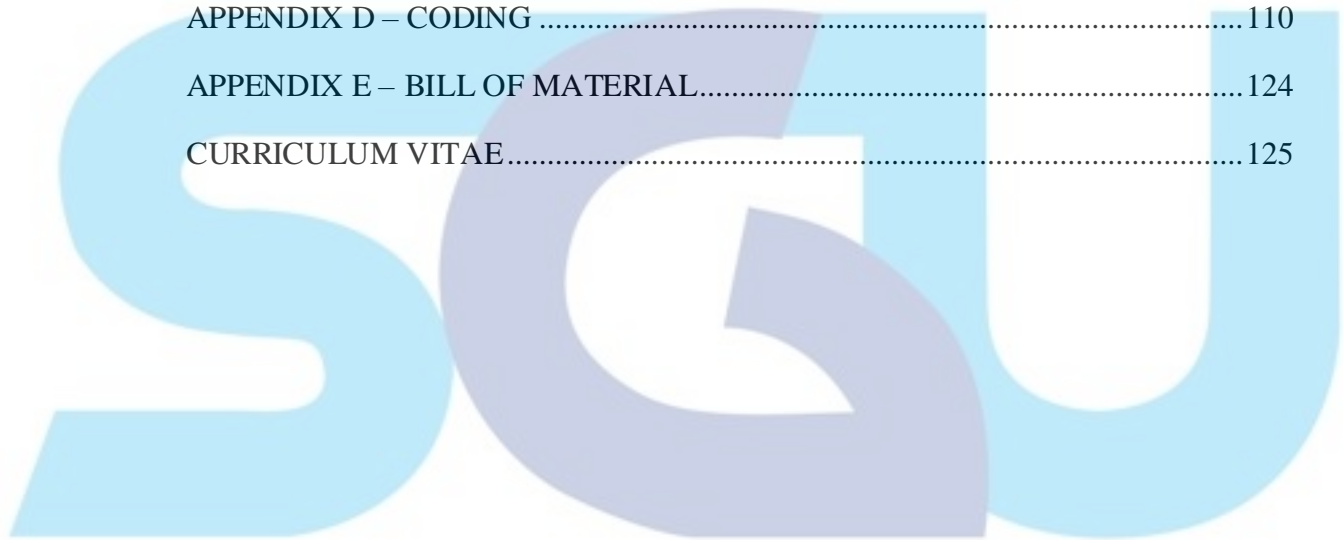
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