DEVELOPMENT OF SWARM ROBOT BASED ON ROBOT OPERATING SYSTEM

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STATEMENT BY THE AUTHOR

I hereby declare that this submission is my own work and to the best of my knowledge, it contains no material previously published or written by another person, nor material which to a substantial extent has been accepted for the award of any other degree or diploma at any educational institution, except where due acknowledgement is made in the thesis.

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ABSTRACT

DEVELOPMENT OF SWARM ROBOT BASED ON ROBOT OPERATING SYSTEM

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The purpose of this thesis is to design a program to follow another robot or any other obstacle that can be recognized by the robot. This thesis also focuses on Robot Operating System (ROS) at which the program will capture the image of the obstacle or another robot and follow it according to the swarm behavior.

Keywords : swarm, robot operating system (ROS), programming)

DEDICATION

I dedicate this work to my family, friends, students of Kumon and the future of Mechatronics Engineering in Swiss German University.

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