

**AUTOMATIC MOTORS-HEIGHT ADJUSTER
FOR SPHERICAL WHEEL**

By

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BACHELOR'S DEGREE
in

MECHANICAL ENGINEERING – MECHATRONICS CONCENTRATION
FACULTY OF ENGINEERING AND INFORMATION TECHNOLOGY

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July 2018

Revision after Thesis Defense on 19th July 2018

STATEMENT BY THE AUTHOR

I hereby declare that this submission is my own work and to the best of my knowledge, it contains no material previously published or written by another person, nor material which to a substantial extent has been accepted for the award of any other degree or diploma at any educational institution, except where due acknowledgement is made in the thesis.

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ABSTRACT

AUTOMATIC MOTORS-HEIGHT ADJUSTER FOR SPHERICAL WHEEL

By

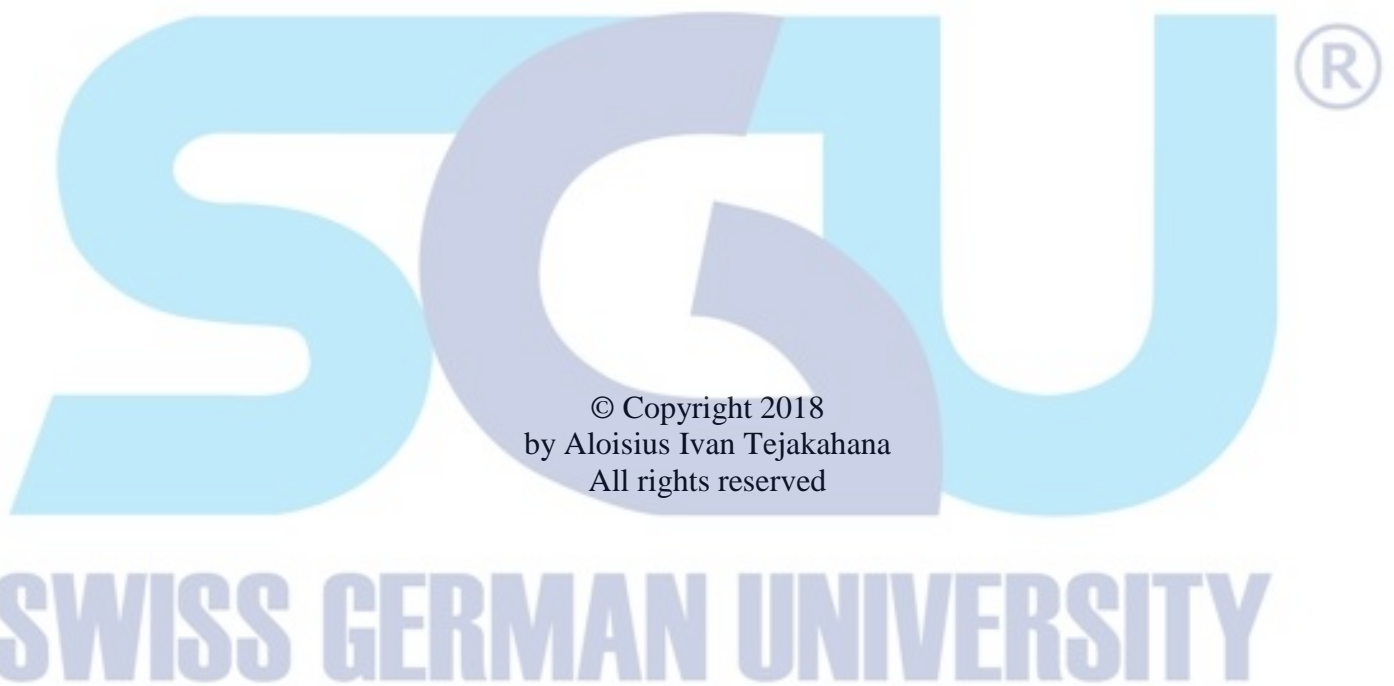
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Spherical wheel wheels are removed for self-balancing spherical wheel project. The motor rollers decrease in height if weight is applied. Designing and constructing the automatic motor's height adjuster is the primary step before the self-balance project.

Three stepper motors and lead-screws are the main components used to control the height of the motor's rollers. Optical mouse sensor is used as a sensor to detect height misalignment in this project. The height adjuster mechanical design is done in SOLIDWORKS. Distance between the mouse's sensor and the ball is important in achieving optimal error detection. The mouse's sensor also needs to be aligned with the equator of the ball. In result, the motor's rollers will align with the ball when the spherical wheel is moving with weight applied. The basketball is used as the spherical wheel's main object for moving and it provides good friction surface.

Keywords: Motors-height Adjuster, Stepper Motor, SOLIDWORKS, Arduino Microcontroller



DEDICATION

I dedicate this works for me, my family, my friends and
the future of the country I loved: Indonesia



ACKNOWLEDGEMENTS

I give many Thanks to God for His blessings throughout the entire thesis work, the strength, patient and bright mind in finding solutions for all challenges and problems.

I give many thanks to my parents, who always support me and encourage me in facing thesis, and prayed for the best for me.

I express my gratitude to my wonderful advisor, Benny Widjaja, S.T., M.T. and Dr. Rusman Rusyadi, B.Sc., M.Sc. for the sincere helps, advices and guidance throughout the thesis work.

I express my thanks also to Yohannes Fredhi Sangadi P., A.Md. and Saiful Afrijal, A.Md. for the helps, advices and guidance in workshop.

Thanks to other lecturers who have given me lessons that are support me in understanding the project.

Thanks to PT. MKT who has contributed their time in manufacturing some parts.

Thanks to Evan Audrian and Albertus Rumawas for advices and supports for problems solving with the spherical wheel project.

Finally, Thanks to all my fellow mechatronics friends for advice and support each other.

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